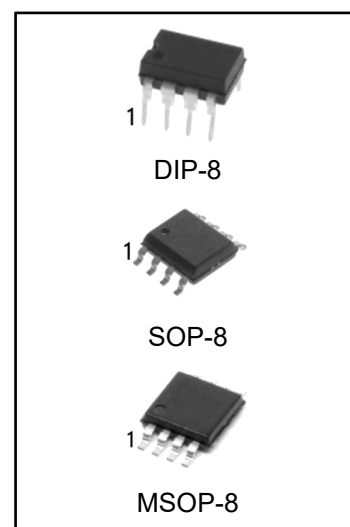


Product Features:

- Good Timing Accuracy
- Strong output driving ability
- Good temperature stability
- The maximum operating frequency can reach over 500KH
Z
- Compatible with TTL circuits
- Packaging form: SOP8、DIP8、MSOP8
- The timing can range from microseconds to hours
(can be precisely controlled through external resistors and capacitors)



Package Information

Product Name	Packaging	Silk Printing Name	Package	Package Quantity
NE555N	DIP-8	NE555	Tube	2000 pcs/ctn
NE555M/TR	SOP-8	NE555	Reel	2500 pcs/reel
NE555MM/TR	MSOP-8	NE555	Reel	3000 pcs/reel
SA555N	DIP-8	SA555	Tube	2000 pcs/ctn
SA555M/TR	SOP-8	SA555	Reel	2500 pcs/reel
SA555MM/TR	MSOP-8	SA555	Reel	3000 pcs/reel

Product Introduction :

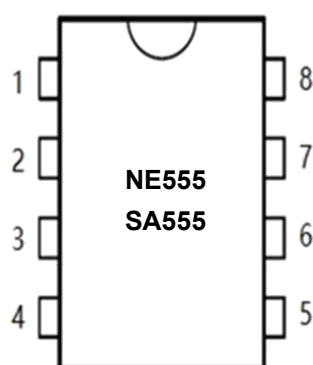
NE555/SA555 is a bipolar integrated circuit that can generate high-precision timing pulses. The internal circuit consists of four parts: threshold comparator, trigger comparator, RS trigger, and output circuit. It can be composed of timing trigger circuits, pulse width modulation circuits, audio oscillators, and other circuits by connecting a small number of external resistive and capacitive devices. Widely used in fields such as toys, signal transportation, automation control, etc.

Product Application :

- Audio pulse generator, frequency divider
- Equipment timing, traffic light control, access control
- Pulse width modulation, pulse phase modulation
- Industrial control

Packaging form :

DIP8/SOP8/MSOP8



Pin Function Definition :

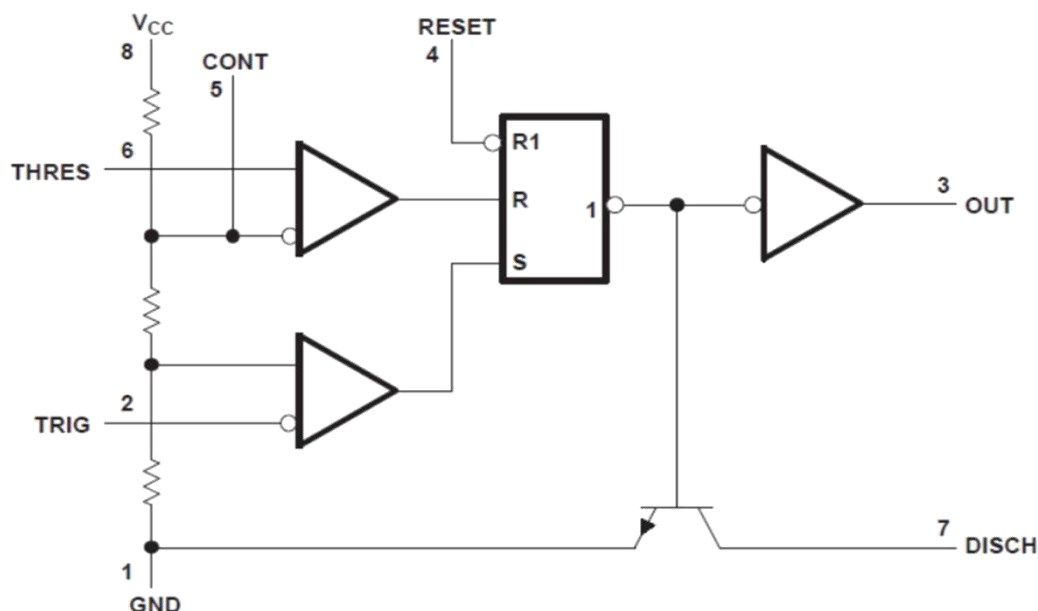
Pin serial number	Pin Definition	Pin Function Description
1	GND	Power supply ground
2	Trig	trigger
3	Output	Output
4	Reset	Reset
5	Cont	Control Voltage
6	Thres	Threshold
7	Disch	Discharge
8	VCC	Power supply positive

Limit Value

Parameter	Symbol	Limit Value	Unit
Power Supply Voltage	VCC	18	V
Input Voltage	VI(thre, trig, cont, reset)	VCC	V
Output Voltage	I _o	±220	mA
Dissipated Power	P _D	400	mW
Operating Temperature NE555	T _A	0 ~ 70	℃
Operating Temperature SA555		-40 ~ 85	℃
Storage Temperature	T _S	-65 ~ 150	℃
Welding Temperature	T _W	260, 10s	℃

Note: Limit parameters refer to the limit values that cannot be exceeded under any conditions. If this limit value is exceeded, it may cause physical damage such as product deterioration; At the same time, it cannot be guaranteed that the chip can operate normally when approaching the limit parameters.

Schematic Diagram



Recommended Electrical Parameters :

Item	Symbol	Parameter Value	Unit
Power Supply Voltage	VCC	4.5 ~ 15	V
Max Input Voltage	V _{th} , V _{trig} , V _{cont} , V _{reset}	VCC	V
Output Current	I _o	±200	mA

Electrical Characteristics : TA=25℃ , (Unless otherwise specified)

Item	Symbol	Condition		Min	Typ	Max	Unit
Operating Voltage	V _{CC}			4.5	-	15	V
Operating Current	I _{CC}	V _{CC} =5V, R _L =∞, V _O =VOL		-	3	6	mA
		V _{CC} =5V, R _L =∞, V _O =VOH		-	1.5	5	mA
		V _{CC} =15V, R _L =∞, V _O =VOL		-	8	15	mA
		V _{CC} =15V, R _L =∞, V _O =VOH		-	6	13	mA
Control Terminal Voltage	V _{CL}	V _{CC} =15V		-	10.0	11	V
		V _{CC} =5V		-	3.3	4	V
Threshold Voltage Terminal Voltage	V _{TH}	V _{CC} =15V		-	10.0	11.2	V
		V _{CC} =5V		-	3.3	4.2	V
Threshold voltage and current	ITH*note1	V _{CC} =15V, V _{TH} =0V		-	-	250	nA
Trigger Terminal Voltage	V _{TRIG}	V _{CC} =15V		-	5.0	5.6	V
		V _{CC} =5V		-	1.6	2.2	V
Trigger terminal current	I _{TRIG}	V _{CC} =15V, V _{TRIG} =0V,		-	-	2	uA
Reset Terminal high voltage	V _{RESETH}	V _{CC} =5V		1.5	-	V _{CC}	V
Reset terminal Low Voltage	V _{RESETL}	V _{CC} =5V		GND	-	0.5	V
Reset Terminal Current	I _{RESET}	V _{RESET} =0.4V, V _{CC} =15V		-	0.13	0.4	mA
		V _{RESET} =0V, V _{CC} =15V		-	0.3	1.5	mA
Output Low Voltage	V _{OL}	V _{CC} =15V, I _L =-5mA		-	0.02	0.25	V
		V _{CC} =15V, I _L =-50mA		-	0.04	0.75	
		V _{CC} =15V, I _L =-100mA		-	2.0	2.5	
		V _{CC} =15V, I _L =-200mA		-	2.8	-	
		V _{CC} =5V, I _L =-5mA		-	0.08	0.35	
		V _{CC} =5V, I _L =-8mA		-	0.15	0.4	
Output High Voltage	V _{OH}	V _{CC} =15V, I _L =-100mA		12.75	13.3	-	V
		V _{CC} =15V, I _L =-200mA		-	12.2	-	
		V _{CC} =5V, I _L =-100mA		2.75	3.3	-	
Discharge tube closing leakage current	I _{dis} (off)	V _O =VOH, V _{dis} = 10V		-	-	100	nA
Discharge Tube Saturation Voltage	V _{dis} (sat)	V _O =VOL	V _{CC} =15V, I _{dis} =15mA	-	140	480	mV
			V _{CC} =5V, I _{dis} =4.5mA	-	100	200	mV
Output rising edge time	t _R	C _L =15pF ,		-	80	300	ns
Output falling edge time	t _F	C _L =15pF		-	50	300	ns
Timing error (monostable state)	T _s *note2	R _A =2kΩ至100kΩ C=0.1uF	V _{CC} =15V, initial error	-	1	-	%
	T _v		Drift with power supply voltage (4.5V ~ 15V)	-	0.1	-	%/V
	T _t		V _{CC} =15V, 随温度漂移 (0 ~ 60℃)	-	150	-	ppm/℃
Timing error (non steady state)	T _s *note2	R _A , R _B =1kΩ至100kΩ C=0.1uF	V _{CC} =15V, initial error	-	1	-	%
	T _v		Drift with power supply voltage (4.5V ~ 15V)	-	0.1	-	%/V
	T _t		V _{CC} =15V, 随温度漂移 (0 ~ 60℃)	-	150	-	ppm/℃

Notes:

- At V_{CC}=15V, the maximum value of R_A+R_B is 10M Ω ; At V_{CC}=5V, the maximum value of R_A+R_B is 3.4M Ω .
- Timing error is defined as the difference between the measured value and the average value of the random sample. At the same time, timing errors are affected by errors in external capacitors and resistors.

Typical application lines

Monostable state: In monostable state mode, when the input level reaches $1/3 V_{CC}$, the circuit triggers the output high level and maintains $t = 1.1 \cdot R_A \cdot C$ for a time, the output becomes low level. During time t , regardless of the input level, the output state is not affected. The circuit and waveform are shown in Figures 3 and 4.

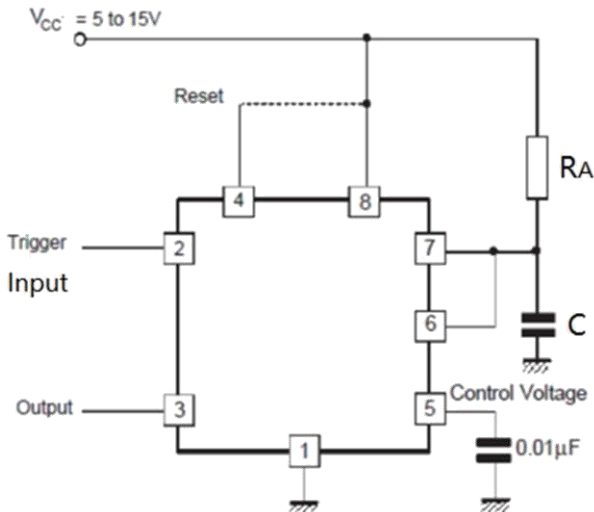


Fig 3 Monostable circuit

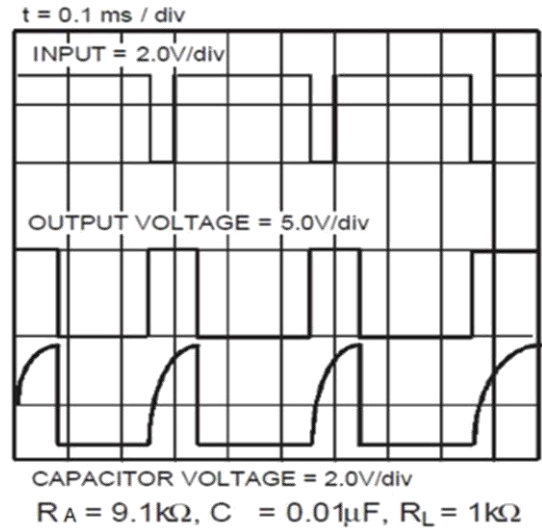


Fig 4 Monostable waveform

Non steady state: In non steady state mode, the circuit will automatically trigger and output as a square wave multi harmonic oscillator. The output square wave frequency and duty cycle can be adjusted by the size of R_A , R_B , and C . The triggering mode, charging and discharging time, and frequency are independent of the power supply voltage. The circuit and waveform are shown in Figures 5 and 6.

Output high-level pulse width $t_h = 0.693 \cdot (R_A + R_B) \cdot C$; Low level pulse width $t_l = 0.693 \cdot R_B \cdot C$; $T = t_h + t_l = 0.693(R_A + 2R_B)C$; Frequency $f = 1/T = 1.44 / (R_A \cdot C + 2R_B \cdot C)$; Duty Cycle $D = t_l / T = R_B / (R_A + 2R_B)$.

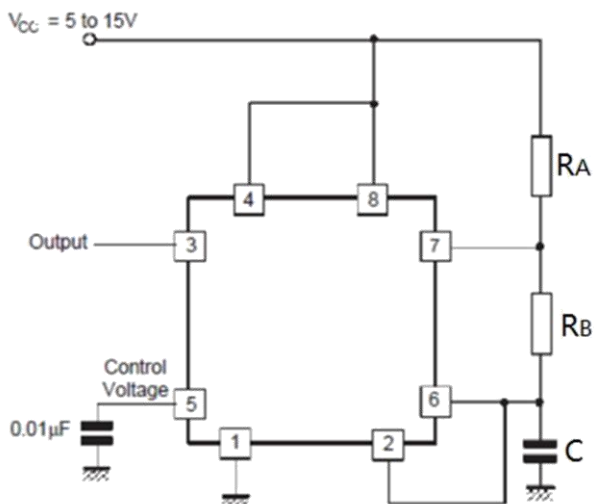


Fig 5 astable circuit

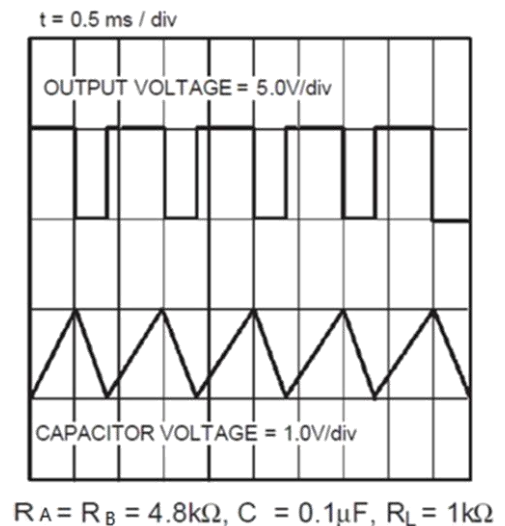


Fig 6 Non-stationary waveform

Pulse width modulation:

When the timer is connected in monostable mode and triggered by a continuous pulse train applied to pin 2, the output pulse width can be modulated by the signal applied to pin 5. See Figures 7 and 8.

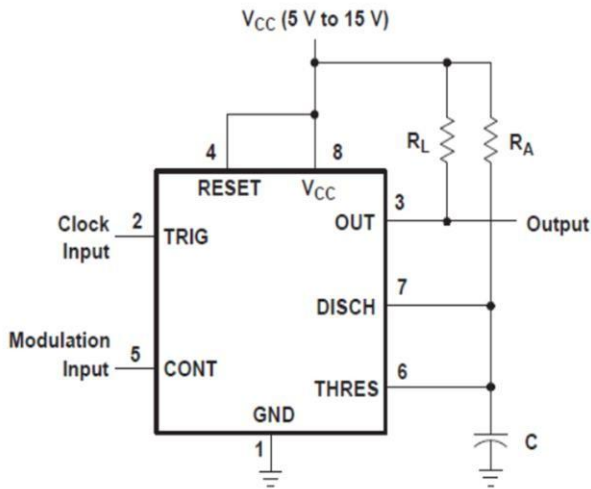


Fig 7 Pulse width modulation circuit

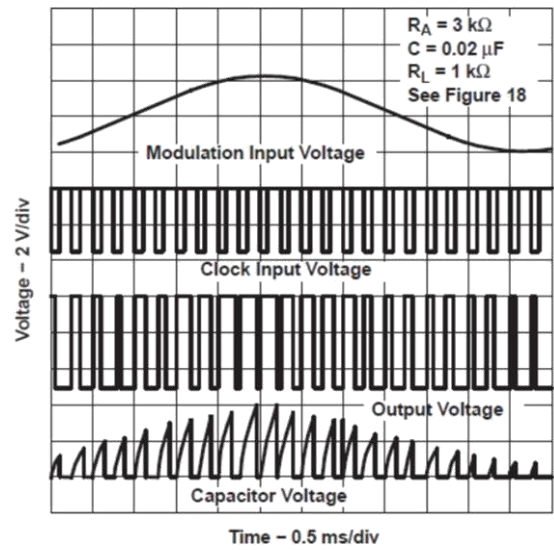


Fig 8 Pulse width modulation circuit waveform diagram

Pulse-position modulation: When the timer is connected by the way in Figure 9, the output pulse position can be modulated by the signal applied to pin 5. See Figures 9 and 10.

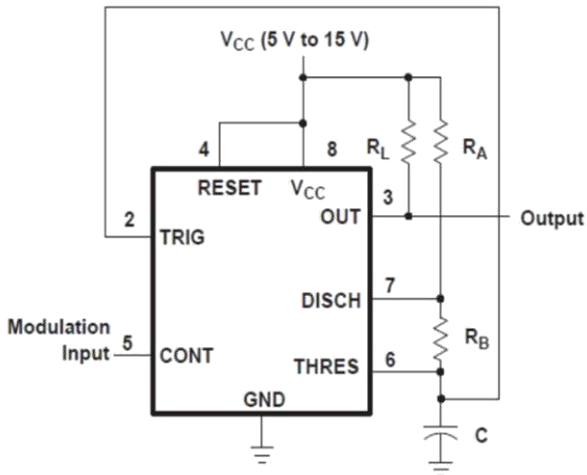


Fig 9 Pulse-position modulation circuit

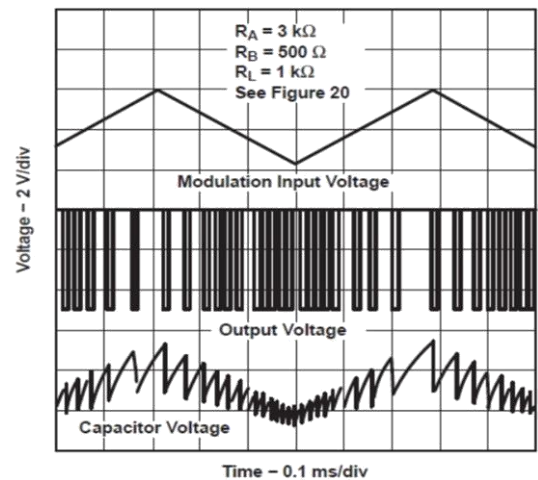
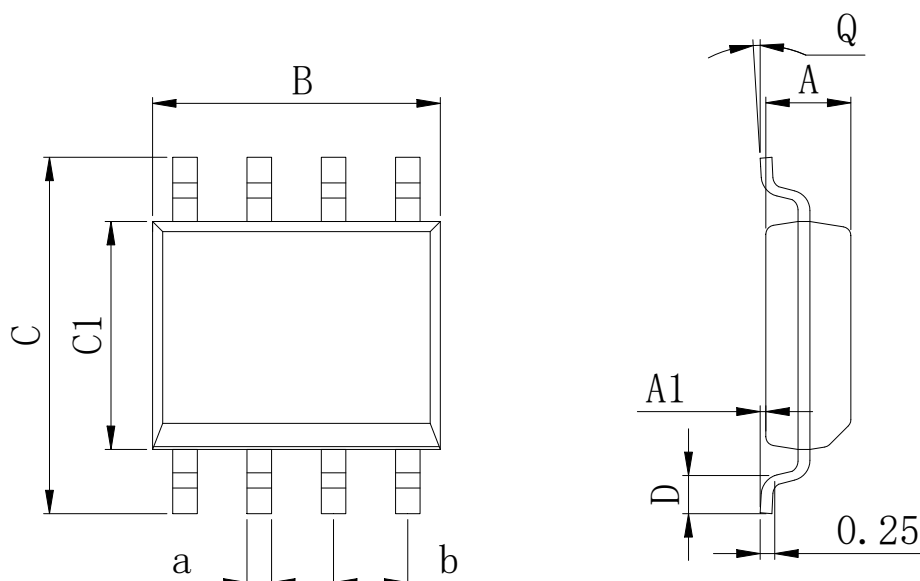


Fig 10 Pulse-position modulation circuit waveform diagram

Packaging Dimensions

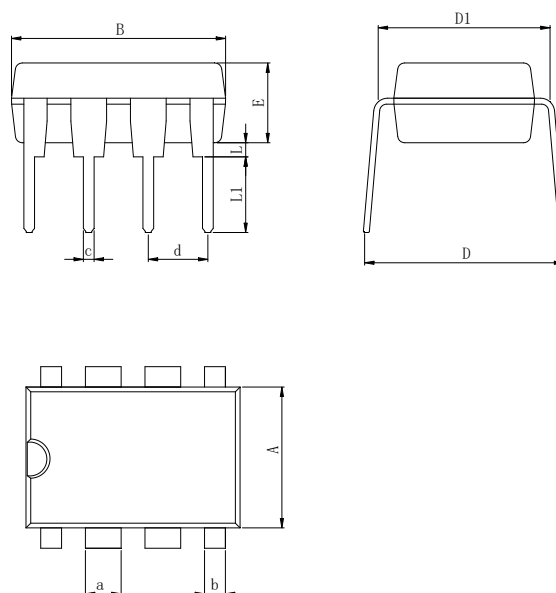
SOP8 (150mil)



Dimensions In Millimeters(SOP8)

Symbol:	A	A1	B	C	C1	D	Q	a	b
Min:	1.35	0.05	4.90	5.80	3.80	0.40	0°	0.35	1.27 BSC
Max:	1.55	0.20	5.10	6.20	4.00	0.80	8°	0.45	

DIP8

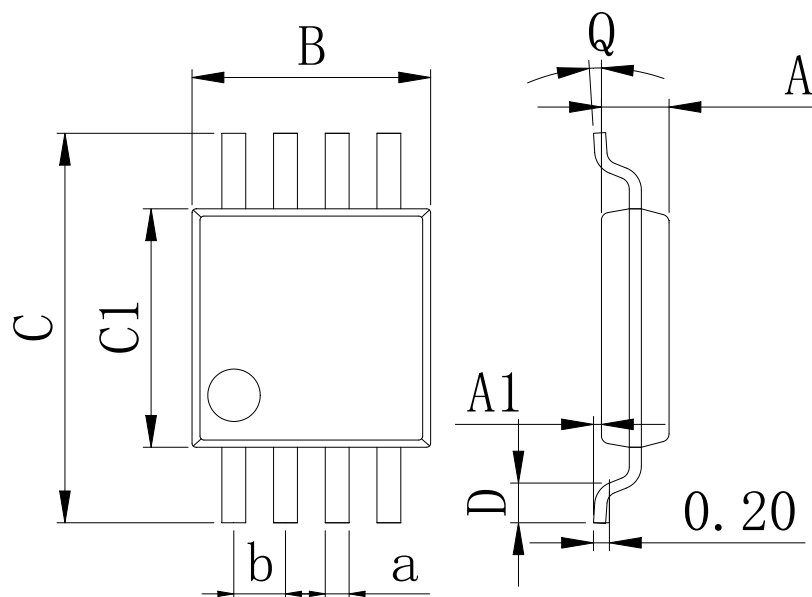


Dimensions In Millimeters(DIP8)

Symbol:	A	B	D	D1	E	L	L1	a	b	c	d
Min:	6.10	9.00	8.40	7.42	3.10	0.50	3.00	1.50	0.85	0.40	2.54 BSC
Max:	6.68	9.50	9.00	7.82	3.55	0.70	3.60	1.55	0.90	0.50	

Packaging Dimensions

MSOP8



Dimensions In Millimeters(MSOP8)									
Symbol:	A	A1	B	C	C1	D	Q	a	b
Min:	0.80	0.05	2.90	4.75	2.90	0.35	0°	0.25	0.65 BSC
Max:	0.90	0.20	3.10	5.05	3.10	0.75	8°	0.35	

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